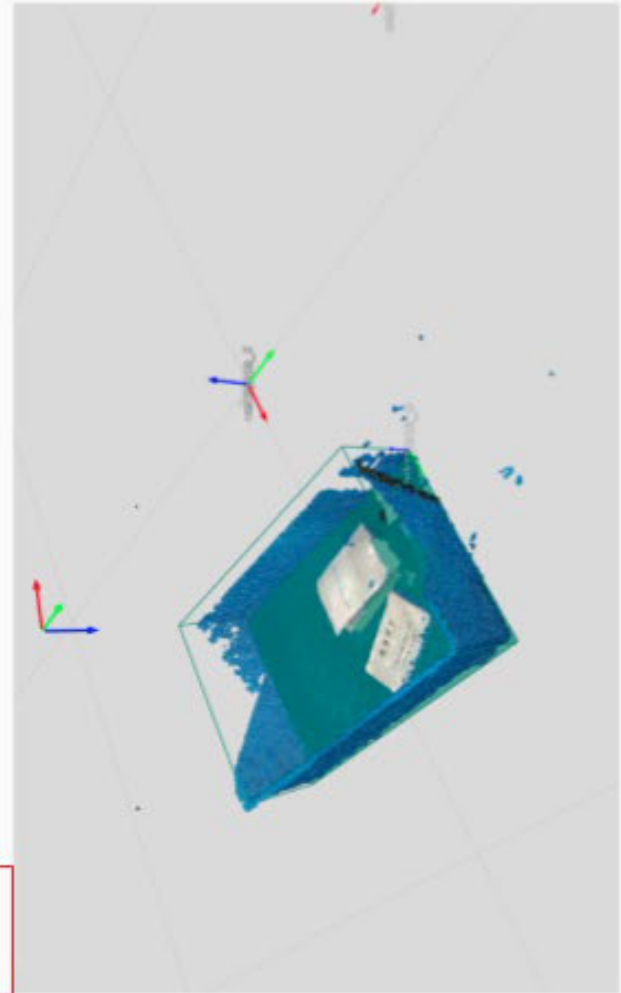


- Camera Calibration
 - Work Space Calibration
 - Visualize Results
- Visualize Calibration Results
- Visualization in 3D to verify and adjust calibration results. Please notice you can enable up to two cameras for displaying pointcloud simultaneously.
- Camera 1
 - Camera 2
 - Camera 3
 - Camera 4
 - Camera 5
 - Camera 6
 - Space 0
 - Space 1
 - Space 2
 - Space 3



Position (mm)	X	Y	Z
	403	280	20

Display Calibration Board

Move robot arm so that calibration board is in camera view. To verify camera calibration results, please press DISPLAY button to visualize a ground truth axis marker. This marker should have its origin in the center (offset deviation within 5mm). Y and Z axis must parallel with board surface as shown below.



DISPLAY

Space 2 Space 3