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Automation Without Intimidation

Unlike other robotic solutions, there is not an expensive integration step to get up and running with our robots. We support many different workflows out of the box, and they can be selected on the fly as your needs change or due to seasonality.

With our GrabIt and TransIt robots, we support a variety of picking workflows:

GrabIt Picking

- Most single items can be picked directly
- Very small or difficult parts (e.g. screws) can be stored in totes, and delivered to stationary picking stations (dynamic AS/RS)

GrabIt Delivery

- Direct delivery to a conveyor, pick cart, or consolidation wall
- Indirect delivery to a Translt robot, a conveyor, pick cart, or consolidation wall

TransIt Receiving

- Standard method of receiving from GrabIt with either boxes or totes of varying sizes depending on order parameters
- Alternatively, can be loaded by a person or other system for arbitrary delivery tasks

TransIt Consolidation Style/Delivery

- Can consolidate each order to a particular box/tote
- Can batch/wave pick and have order consolidation be done at a later point
- · Can deliver full totes/boxes to a conveyor or shelf

Benefits Beyond Direct Cost Comparisons

Many cost aspects of the current system were ignored in this analysis. If they were included, the value provided would be even more significant. These include the following:

- Management costs of picking labor
- Barcode scanners
- · Returns for wrong items
- Shrinkage
- HR overhead
- Personnel injury/liability
- Heating/cooling costs

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